

Implications of Nanodevice Mobility on Terahertz Communication Links in the Human Vessels

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ABSTRACT

This paper describes the time-varying nature of terahertz communication links between mobile nanodevices, targeting a realistic use case for nanodevice communication within human vessels. We consider a communication link through dipole-like nanoantennas, which flow and rotate in the bloodstream. Such a dynamic scenario causes random glitches in the received power level, resembling a fading-like channel. We present an analytic formulation for the time-variant impulse response and calculate performance metrics like the level crossing rate and the average fade duration. Our findings reveal crossings in the millisecond order and an average duration of fades on the same scale. Our study is the basis for designing robust decoders and error-correcting codes that mitigate the impact of variability on the received power level.

CCS CONCEPTS

• Applied computing → Health informatics; • Hardware → Biology-related information processing.

KEYWORDS

Terahertz, Nanoantenna, Human vessels, Time-varying channel

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1 INTRODUCTION

Electromagnetic (EM) waves in the terahertz (THz) band are enabling a multitude of new healthcare applications at the nanoscale. Examples are suppressing undesired interactions in proteins [2] and

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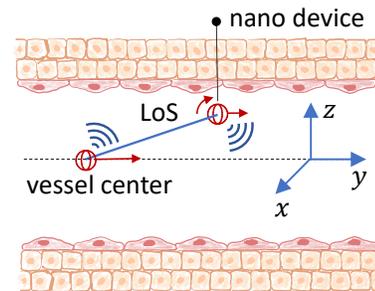


Figure 1: Mobility and rotation of nanodevices along vessel segments in the circulatory system.

creating 3D images of red blood cells [6]. The THz nanocommunication systems also enable information transfer between nanodevices in the human body [9]. To that end, THz radio frequency (RF) front-ends are today conceived through plasmonic nanoantennas with dipole-like [8, 15], patch [16], and spiral geometry [3] designs.

A key aspect of the communication link between nanodevices is the time-varying nature of the channel in the human vessels. Nanodevices drifted by the bloodstream will experience a time-varying distance between each other. In addition, the nanoantennas may rotate, misaligning the transmitter and receiver radiation patterns; see Fig. 1. This dynamic position and rotation produce a fluctuating power level of the received signal, negatively affecting communication performance; which is yet to research.

Existing models for the in-body links predict the communication performance in the blood [7], but the time-varying nature of the channel has not been explored in detail. As we will show in this paper, when evaluating the communication link in the arterioles, the varying distance produces a variability of the received signal in a millisecond (ms) time-scale, while the rotation of the nanoantennas produces a much faster variability in the same time-scale. This variability will be reflected in the amplitude of the received signal, which will be observed as glitches falling below the receiver's sensitivity level. The impact of the blood flow dynamics on the communication link will, therefore, result in a fading-like channel impacting the communication performance.

Aiming at describing the communication link between nanodevices in the blood flow, this paper extends our previous research in [17] to investigate the two most relevant related metrics regarding the channel time-variability: the level crossing rate (LCR) and

the average duration of fades; see [11, Sec. 4.7.3]. The LCR provides the frequency of crossings of the received power through the threshold sensitivity. When the received signal is below the receptor’s sensitivity, the communication will be interrupted as the signal can no longer be decoded. Meanwhile, the average duration of fades provides the time duration of the interrupted link, where the received power is below the sensitivity of the receiver.

The presented study supports the further development of reliable communication schemes. As our findings illustrate, the channel resembles a fast-fading link, which requires implementing robust receptors to diminish the impact of fluctuations in the received signal level as in the case of mobile communications [1].

Our main contributions can be summarized as follows:

- We provide an analytic description for the time-varying channel in a link between two nanodevices that flow in the human vessels,
- we derive the theoretical calculations for the LCR and the average duration of fades, and
- we illustrate with realistic parameters the resulting LCR and average duration of fades.¹

2 SYSTEM MODEL

Since we address an EM communication link in the blood vessels between two nanodevices, the system model includes mainly three components: (1) The RF front-end of the nanodevices, (2) the mobility of the nanodevices within the blood flow, and (3) the path loss attenuation within blood in the THz band. These components are described in the next subsections.

2.1 RF Front-End

The nanodevices are equipped with dipole-like nanoantennas following the design by Tamagnone et al. [15]. The nanoantenna comprises two radiator patches made of graphene and a substrate made of quartz with the dimensions listed in Table 1.² The design is shielded in a spheric cover made of polydimethylsiloxane (PDMS) with a radius $r = 35.7 \mu\text{m}$. In our simulation in CST Studio Suite 2021, the shielded nanoantenna is surrounded by blood to evaluate the radiation pattern; see the complete design in Fig. 2 and further details in [17]. The resulting radiation pattern is illustrated in Fig. 3 yielding a gain in the range -40 to -12 dBi with a resonant frequency $f_c = 2.107$ THz.

2.2 Piezoelectric Nanogenerator

We evaluate the transmission power based on piezoelectric nanogenerator technologies, as reported in [10]. These nanogenerators harvest mechanical energy due to the contraction of ZnO nanowires produced by the interaction with pressure waveforms, like the ones in human vessels. This generator has a power density of $83 \text{ nW}/\text{cm}^2$, where we assume it is deployed along the bottom side of the cover surface in Fig. 2. This area is calculated as $A_g = 4\pi r^2/2 \approx 8 \times 10^{-9} \text{ m}^2$. Following these calculations, the resulting transmitter power is $P_{\text{Tx}} = -90$ dBm. To cope with this low

¹We provide open access to the nanoantenna design in CST Studio Suite 2021 as well as the mobility model in Matlab 2023b code at https://github.com/jorge-torresgomez/terahertz_inbody

²Future work will evaluate other antenna’s geometries as listed in the Introduction.

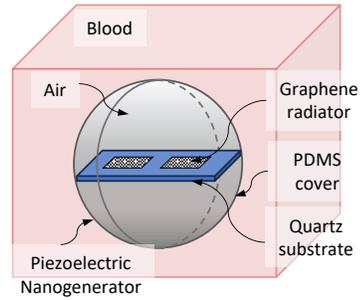


Figure 2: The antenna is modeled in CST as being shielded within a sphere made of biocompatible PDMS material, surrounded by blood.

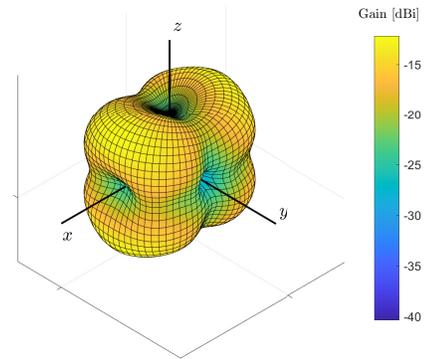


Figure 3: Radiation pattern of the nanoantenna inserted in blood.

power level at the receiver, we assume the lowest sensitivity level on wireless technologies for the nanosensor, as the case in global navigation satellite system (GNSS), which set a sensitivity value of -165 dBm as a requirement.³

2.3 Mobility Model for the Nanodevices

The mobility of the nanosensor will comprise two components: displacement and rotation. Regarding the displacement component, we assume the nanodevices travel in the arterioles, where the vessel thickness is $h_v = 200 \mu\text{m}$ and the maximum speed is $v_c = 0.1 \text{ cm}/\text{s}$ along the vessel center; see [5, Table I]. In this mobility scenario, the spherical nanodevices will follow a straight path along the vessel stream, i.e., advection dominates diffusion. See this evaluation with the corresponding Péclet number in [17, Eq. (5)].

For simplicity and without loss of generalization, we assume the receiver node travels along the vessel center at the corresponding blood speed $v_c = 0.1 \text{ cm}/\text{s}$. The transmitter node travels at $90 \mu\text{m}$ away from the center and with initial distance $108 \mu\text{m}$ away from the receiver. Along this vessel stream, the emitter travels at the less speed $0.02 \text{ cm}/\text{s}$; after evaluating [17, Eq. (3)]. Within this settings, the receiver will forward the transmitter position in the y -direction due to the larger traveling speed. Besides, for ease of calculation,

³Future work will investigate the developments in nanoreceiver technologies in the THz band.

where θ is the elevation angle, and ϕ is the azimuth coordinate. The value of $L_v(t)$ is the path loss in the channel as given with Eq. (1).

The transmitter and receiver's gain are evaluated according to the rotation and displacement of the antennas, as produced by the fluid; see Fig. 1. Both gains must be evaluated in the line of sight (LoS) link between both devices, as represented with the blue line in Fig. 1. Here, we assume a negligible impact of reflections in the vessel walls due to the larger path loss. As for the receiver's gain, the evaluated gain will be given by the elevation and azimuth angles, as given by the LoS direction with the receiver, yielding

$$g_{Rx}(t) = G(\theta_{Rx,init} + \theta_{Rx}(t), \phi_{Rx,init} + \phi_{Rx}) \quad (5)$$

where the values of $\theta_{Rx,init}$ and $\phi_{Rx,init}$ refer to the initial orientation of the antenna, which we assume to follow a random variable with uniform distribution in the range $[-\pi, \pi]$. The value of θ_{Rx} and ϕ_{Rx} , which refer to the LoS link with the transmitter, are evaluated while transforming the cartesian coordinates for the LoS direction to the spherical coordinates as follow

$$\begin{aligned} \theta_{Rx}(t) &= \tan^{-1} \frac{Tx_{posz}}{|\mathbf{Tx}_{pos}(t) - \mathbf{Rx}_{pos}(t)|}, \\ &= \tan^{-1} \frac{Tx_{posz}}{\sqrt{(Tx_{posy,0} + (v(Tx_{posz}) - v_c) \times t)^2 + Tx_{posz}^2}}, \\ \phi_{Rx} &= \tan^{-1} \frac{Tx_{posy}(t) - Rx_{posy}(t)}{Tx_{posx} - Rx_{posx}} = \frac{\pi}{2}. \end{aligned} \quad (6)$$

In the above relations, the azimuth component (ϕ) evaluates as $\frac{\pi}{2}$ as both antennas are moving in the yz -plane. As for the elevation component (θ), the denominator evaluates the distance with the transmitter and receiver coordinates denoted with the vectors $\mathbf{Tx}_{pos}(t)$ and $\mathbf{Rx}_{pos}(t)$, respectively. Along the y -axis the transmitter location will be given by $v_c \times t$, and the transmitter location as $(Tx_{posy,0} + v(Tx_{posz}) \times t)$, where $v(Tx_{posz})$ is evaluated with [17, Eq. (3)], and $Tx_{posy,0}$ is the initial position of the emitter in the y -axis. Along the z -axis, the transmitter coordinate is constant as Tx_{posz} , while the receiver is zero. In these relations, we implicitly assume that the system coordinates are centered at the initial receiver coordinates and the z -axis oriented in the plane where the transmitter is moving, see Fig. 1.

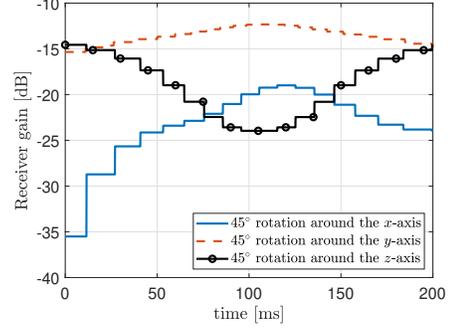
As for the transmitter, the displacement and the rotation will significantly modify the time evolution of the gain. Similarly to the receiver, we evaluate the gain having the initial angle and the time-evolution of the elevation and azimuth angles as follows

$$g_{Tx}(t) = G(\theta_{Tx,init} + \theta_{Tx}(t), \phi_{Tx,init} + \phi_{Tx}), \quad (7)$$

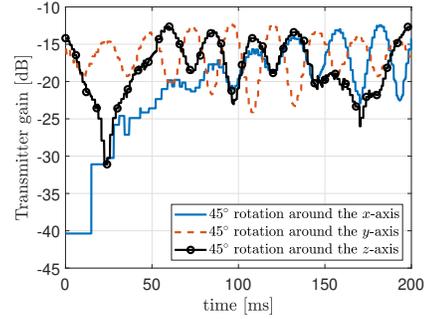
where

$$\begin{aligned} \theta_{Tx}(t) &= \tan^{-1} \frac{Tx_{posz}}{|\mathbf{Tx}_{pos}(t) - \mathbf{Rx}_{pos}(t)|} + \pi - \dot{\omega} \times t, \\ &= \tan^{-1} \frac{Tx_{posz}}{\sqrt{(Tx_{posy,0} + (v(Tx_{posz}) - v_c) \times t)^2 + Tx_{posz}^2}} \\ &\quad + \pi - \dot{\omega} \times t, \\ \phi_{Tx} &= \tan^{-1} \frac{Rx_{posy} - Tx_{posy}}{Rx_{posx} - Tx_{posy}} = \frac{\pi}{2}. \end{aligned} \quad (8)$$

In this evaluation, the azimuth component (ϕ_{Tx}) also evaluates as $\frac{\pi}{2}$ as the transmitter is moving in the yz -plane. As for the



(a) Receiver gain for various initial angles



(b) Transmitter gain for various initial angles

Figure 5: Receiver and transmitter gains for various initial angles.

elevation component ($\theta_{Tx}(t)$), the expression includes the time-varying distance between the emitter and the receiver with the term $(|\mathbf{Tx}_{pos}(t) - \mathbf{Rx}_{pos}(t)|)$. Besides, in contrast to the receiver, this expression also includes the rotation produced by the fluid with the term $\dot{\omega} \times t$.⁵ We include this term with a negative sign to follow the clockwise direction of the rotation. Finally, we add the constant π , evaluating the direction from the emitter to the receiver.

Following Equations (6) and (8), the transmitter and receiver gains will be impacted not only by the time-varying distance between the emitter and the receiver but also by its antenna orientation. To illustrate this variability, Fig. 5a depicts the receiver gain with time and for various initial angles along the three axes. The time evolution of the gain will be highly dependent on the initial angle for the nanoantenna. The degree of variability of the transmitter gain with time is in the order of ms, as it is impacted by the blood fluid speed, which is in the magnitude's order of cm/s; see Table 1. The transmitter gain exhibits a more speedy variability in the same order's magnitude of the ms, which is due to the rotation and the variability of the radiation pattern surface; see the evaluation with Fig. 5b.

⁵Note that the rotation term does not appear with the receiver formulation in Eq. (6), since it travels in the vessel center, where the torque force is zero.

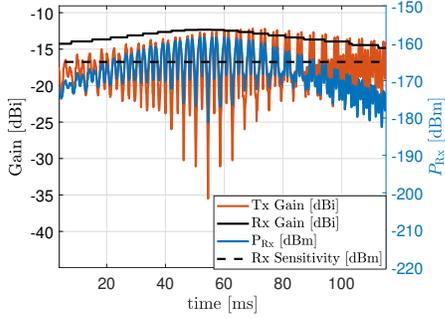


Figure 6: Received power and antenna gain over time as the nanoantennas flow with the blood.

4 LEVEL CROSSING RATE AND AVERAGE FADE DURATION

The variability of the channel amplitude with time induces the amplitude variability of the received signal. To illustrate, Fig. 6 depicts the variability of the transmitter and receiver gain, as well as the received power. As a result of this variability, the received power level is

$$P_{dB}(t) = P_{Tx} + G_{Tx,dB}(t) + G_{Rx,dB}(t) - L_{v,dB}(t), \quad (9)$$

which is also dependent on the mobility and rotation of antennas. The amplitude of the received signal resembles small-scale fading as its level abruptly falls below the receiver sensitivity value.

To account for the quality of the communication link, in this section, we develop the LCR and the average fade duration in the link; see [11, Sec. 4.7.3]. The LCR refers to the average number of times when the power level crosses a given sensitivity value, here denoted as R_{th} , and calculated as [13, Eq. (4.1)]

$$N_R(t) = \int_0^\infty \dot{r} p\{R_{th}, \dot{r}, t\} d\dot{r}, \quad (10)$$

along the time interval $[t, t + dt]$, where \dot{r} is the time derivative of the received power, and $p(\dot{r}, R_{th}, t)$ is the joint Probability Density Function (PDF) of \dot{r} and the received power level r at $r = R_{th}$.

We evaluate $p\{R_{th}, \dot{r}, t\}$ numerically, and mostly accounting for the impact of the transmitter variability. As depicted in Fig. 5, the variability of the transmitter gain is faster than the emitter and the channel path loss in Fig. 4. Under these assumptions, we calculate \dot{r} as

$$\dot{r}(t) \approx \frac{1}{\Delta t} \frac{\mathbb{E}\{g_{Rx}(t)\}}{L_v(t)} (g_{Tx}(t + \Delta t) - g_{Tx}(t)), \quad (11)$$

with $r = a^2(t)$ (see Eq. (4)), assuming $g_{Rx}(t + \Delta t) \approx g_{Rx}(t)$ and $L_v(t + \Delta t) \approx L_v(t)$, when Δt is in the ns scale. Besides, we evaluate the expected average for the receiver gain to account for all possible initial orientation angles. This expected value (≈ -18.4 dBi) is evaluated numerically with the histogram of values for the radiation pattern $G(\theta, \phi)$; see Fig. 7.

We compute the difference $(g_{Tx}(t + \Delta t) - g_{Tx}(t))$ first calculating the $g_{Tx}(t)$ value that evaluates the threshold level R_{th} in the received power. We calculate $g_{Tx}(t) = g_{Tx,th}$ equating $P_{dB}(t) = R_{th}$ in Eq. (9) and also evaluating $G_{Rx,dB}(t)$ with its expected value (≈ -18 dB). From this point in the radiation pattern surface, we evaluate all the possible other points $g_{Tx}(t + \Delta t)$ from $g_{Tx,th}$. We assume all these points are those with elevation angles at $\Delta\theta = \omega \times \Delta T$ [rad]

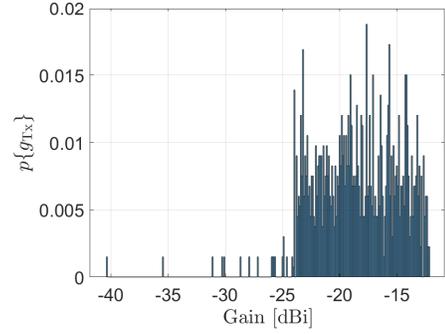


Figure 7: Numerical evaluation of the probability $p\{g_{Tx}\}$

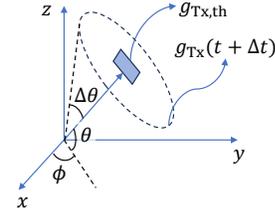


Figure 8: Illustration of gain values around the threshold gain $g_{Tx,th}$.

from $g_{Tx,th}$, as we assume the arbitrary orientation of the initial antenna position, see an illustration in Fig. 8. From this specific value, other reachable points will be located in the range -22 to -18 dBi. Following this sequence of points for $g_{Tx}(t + \Delta t)$, we evaluate the histogram to estimate $p\{R_{th}, \dot{r}, t\}$ numerically.

Once the LCR metric is calculated with Eq. (10), the average duration of fading is readily evaluated as [11, Eq. (4.81) pp. 186]

$$\mathbb{E}\{\tau\} = \frac{1}{N_R} p\{r < R_{th}\}, \quad (12)$$

where $p\{r < R_{th}\}$ is the probability that the received power level is less than the receptor's sensitivity, here denoted as R_{th} . We evaluate this probability with a similar procedure as for the LCR with the histogram of values in the antenna gain. We find the minimum value of the transmitter gain $g_{Tx,th}$ that fulfills $P_{dB}(t) = R_{th}$. Then, we numerically evaluate the integral $\int_0^{g_{Tx,th}} P(g) dg$ as a result of the probability $p\{r < R_{th}\}$, where $P(g)$ is estimated with the histogram of values for the antenna gain.

5 RESULTS

This section illustrates the two performance metrics, LCR and the average fade duration, with the nanodevice's position. We develop their numerical calculation with the description given in Section 4. In this evaluation, we consider that $t = 0$ refers to the case for the initial position of the transmitter and receiver nanodevices, where the emitter is at a forward position, as illustrated in Fig. 1. As time increases, the receiver moves faster as it travels through the vessel center; thereby, the channel path loss also decreases with time until it increases again when the receiver forwards the emitter node; see Fig. 4 for the time evolution of the path loss.

In the vicinity of the minimum path loss, we found the LCR around the 200 crossings/ms. Once the LCR is calculated, the average duration of fades is numerically evaluated with Eq. (12). The

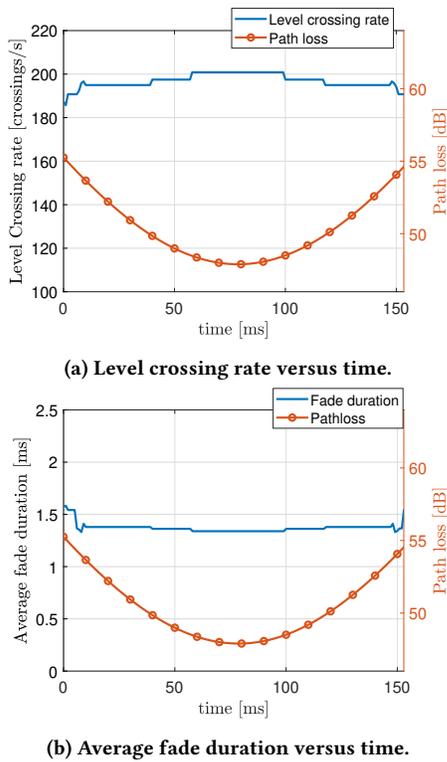


Figure 9: LCR and average fade duration metrics.

average duration of fades is illustrated in Fig. 9b, where the duration of fades is around 1.5 ms. The results in Fig. 9a characterize a medium- to fast-fading channel when the pulse emission is performed with a bandwidth in the order of the MHz. For this emission rate, there is one observed glitch per received pulse on average. Besides, according to the results in Fig. 9b, this channel characterizes a large-scale fade-like when the duration of pulses is less than ms scale. Due to these results, such a communication link would require designing receivers while including a channel estimator component, so to avoid emissions during the fading time-interval.

6 CONCLUSION

In this paper, we assessed the time-varying communication link between nanodevices moving in the human circulatory system. The analytical expressions introduced in this paper target a realistic link as we now also include in the radiation pattern of nanoantennas inserted in blood and the impact of mobility. We observed a medium to fast-fading channel in the THz band and also a large-scale fading behavior when performing emissions at a MHz rate and with a pulse duration in the ns scale. This eventually demands channel compensation mechanisms to neglect the impact of glitches in the received sequence and robust schemes to overcome large-scale fading. The methodology introduced can be straightforwardly extended to other antenna designs and mobility scenarios in the vessel segments, which is part of our future research directions.

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